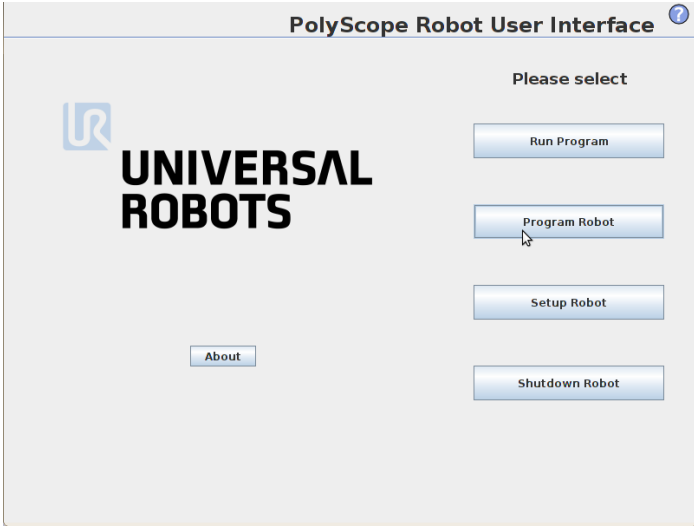
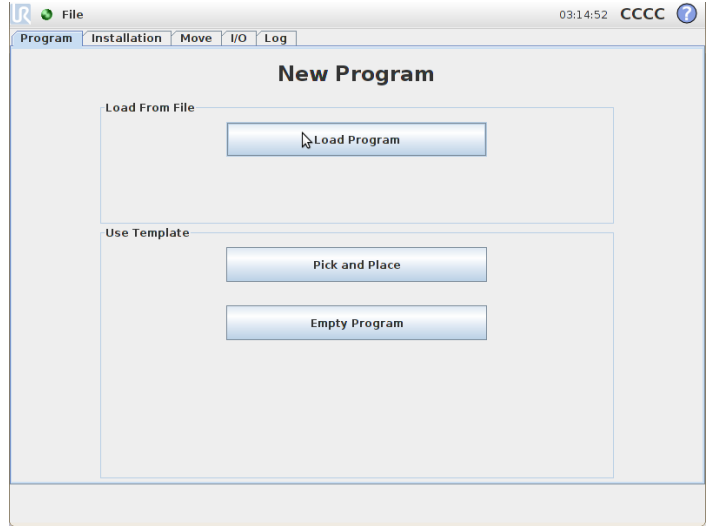


To get started with your new RG2 gripper. Mount and connect the gripper and turn on the robot. Put in the USB drive and wait a few seconds. The software will be uploaded automatically to the UR robot.

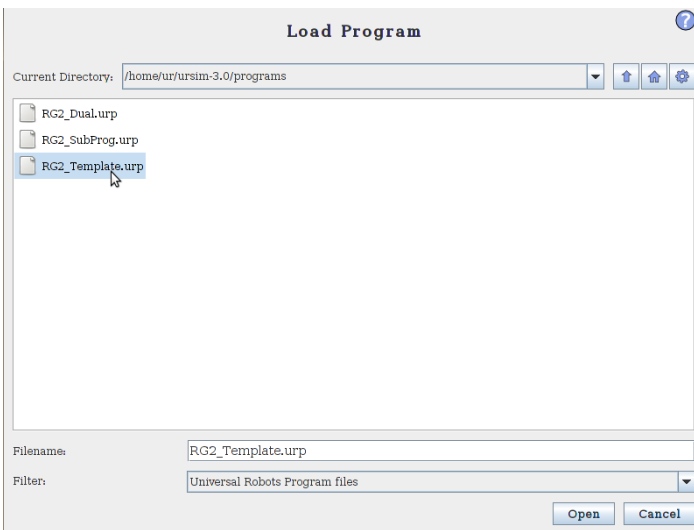
1. Select **Program Robot**



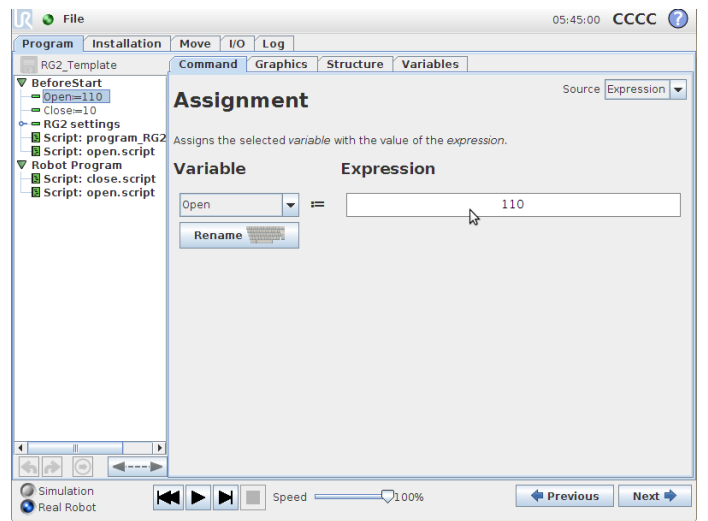
2. Select **Load Program**



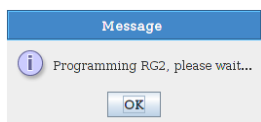
3. select **RG2\_Template.urp**, Click **Open**



4. In the **Program** tree, set the desired gripping width for **Open** and **Close** in the corresponding **Expression** box.



5. Press **Play**  The



popup will appear. After approximately 3 seconds, the gripper will start opening



**WARNING:** It is important that the user/implementer of this product have read and understood the manual before connecting the gripper to any equipment.