

YRG Series

Product Lineup

ELECTRIC GRIPPERS

Electric grippers dedicated to the RCX240/RCX340 controller. Easy operation is achieved as YAMAHA robot language gives unified control.



Gripping force control

Gripping force can be set in 1 % steps from 30 to 100 %.

Measuring

Workpiece can be measured using position detection function.

Speed control

Speed can be set in 1 % steps from 20 to 100 % and acceleration can be set in 1 % steps from 1 to 100 %.

Multi-point position control

Up to 10,000 positioning points can be set.

Workpiece check function

Workpiece gripping mistake or workpiece drop can be checked by the HOLD output signal without using sensor.

Plenty of lightweight and compact model variations

S type Single cam type

P.585

Lightweight, compact, high-speed



Single cam structure
Use of a unique cam structure achieves the simple and compact design. As the self-lock is not activated, the fingers can be operated using an external force.

W type Double cam type

P.587

High gripping force



Double cam structure
Unique double cam structure with gear. Use of a simple structure achieves high gripping force with compact body.

Screw type Straight shape

P.588

High accuracy, long stroke



Ball screw structure
As the ground ball screw is driven by the belt, the long stroke with high efficiency and high accuracy is achieved.

Screw type "T" shape

P.589

Three fingers type

P.590

Compact, high rigidity, long stroke



Compact ball guide structure
Use of a special cam provides lightweight and compact electric grippers. These electric grippers are suitable for transfer of round workpieces made of glass or similar materials.

Type	Model	Gripping force(N)	Open/close stroke (mm)	Maximum speed (mm/sec.)	Repeated positioning accuracy (mm)	Main body weight (g)	Page
Compact single cam	YRG-2005SS	5	3.2	100	+/- 0.02	90	P.585
Single cam	YRG-2010S	6	7.6	100	+/- 0.02	160	P.586
	YRG-2815S	22	14.3	100	+/- 0.02	300	
	YRG-4225S	40	23.5	100	+/- 0.02	580	
	YRG-2005W	50	5	60	+/- 0.03	200	
Double cam	YRG-2810W	150	10	60	+/- 0.03	350	P.587
	YRG-4220W	250	19.3	45	+/- 0.03	800	
	YRG-2020FS	50	19	50	+/- 0.01	420	
Screw type Straight shape	YRG-2840FS	150	38	50	+/- 0.01	880	
Screw type "T" shape	YRG-2020FT	50	19	50	+/- 0.01	420	P.589
	YRG-2840FT	150	38	50	+/- 0.01	890	
Three fingers type	YRG-2004T	2.5	3.5	100	+/- 0.03	90	P.590
	YRG-2013T	2	13	100	+/- 0.03	190	P.591
	YRG-2820T	10	20	100	+/- 0.03	340	
	YRG-4230T	20	30	100	+/- 0.03	640	

- Gripping force control: 30 to 100 % (1 % steps)
- Speed control: 20 to 100 % (1 % steps)
- Acceleration control: 1 to 100 % (1 % steps)
- Multi-point position control: Maximum 10,000 points
- Workpiece size judgment: 0.01 mm steps (by ZON signal)

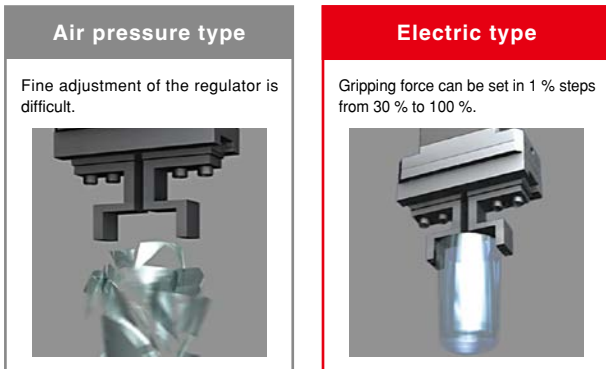
POINT 1

Electric grippers achieve highly accurate gripping force, and position, and speed controls.

The YRG series provides the gripping force control, speed and acceleration controls, multi-point control, and workpiece measurement that were difficult by conventional air-driven devices. The YRG series flexibly supports various applications.

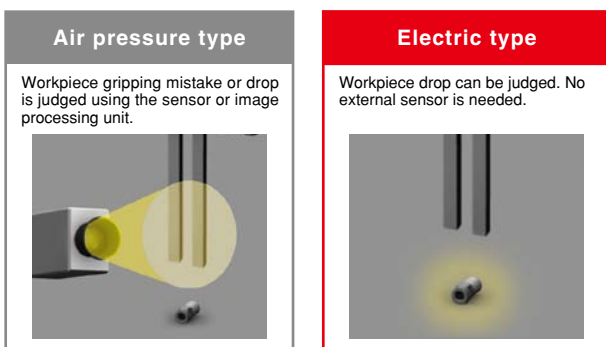
Gripping force control

The gripping force can be set in 1 % steps. Workpieces that are easy to break or deform, such as glass or spring can be gripped. The gripping force is constant even when the finger position changes.



Workpiece presence check function

The electric gripper outputs the HOLD signal. Workpiece gripping mistake or workpiece drop during transfer can be checked. No external sensors are needed.



Speed control

The speed and acceleration can be set in a range of 20 to 100 mm/sec. in 1 % steps (single cam and three fingers type). The gripper can gently touch workpieces that are vulnerable to impact, such as lenses or electronic components.

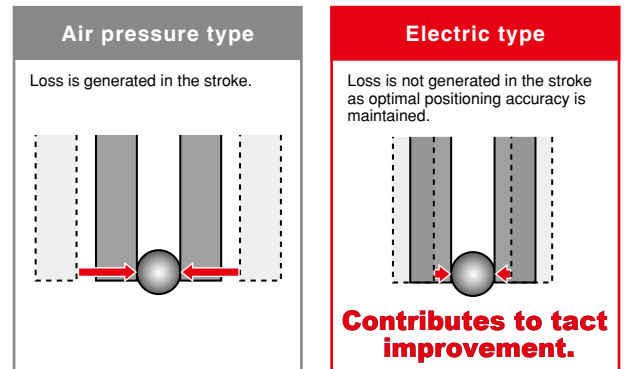
POINT 2

Gripper can be controlled with controller commands.

The gripper controls can be performed with one multi-axis controller RCX240/RCX340. Data exchanging with the host unit, such as PLC is not needed. The setup or startup can be made easily.

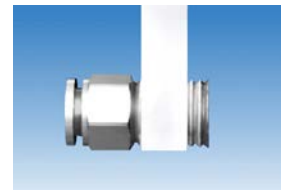
Multi-point position control

The finger can be set to a desired position according to the workpiece size. This contributes to efficiency improvement of lines with different workpiece sizes and materials mixed and lines with many setup steps.



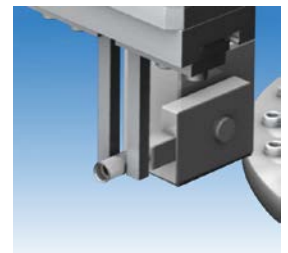
Measuring function

The gripped workpiece can be measured using the position detection. Use of this function makes it possible to correctly judge what portion of the workpiece is gripped.



Zone range function

Use of this zone range function makes it possible to judge the size OK/NG and check for slant insertion.



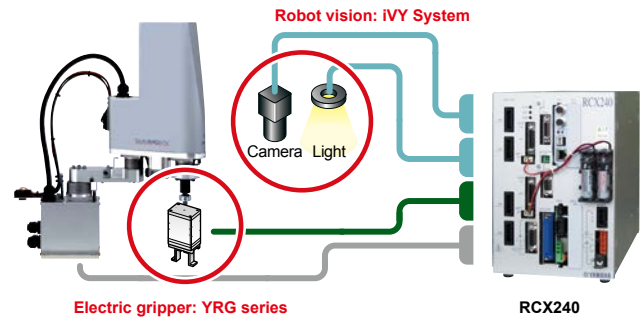
List of robot languages (example)

Language name	Function
GDRIVE	Absolute position movement
GDRIVEI	Relative position movement
GHOLD	Absolute position gripping movement
GHOLDI	Relative position gripping movement
GOPEN	Constant speed gripping movement (open)
GCLOSE	Constant speed gripping movement (close)
GORIGIN	Gripper axis return-to-origin
GSTATUS	Status acquisition
ORIGIN	Return-to-origin
WHERE	Main group current position acquisition (joint coordinate: pulse)
WHERE2	Sub group current position acquisition (joint coordinate: pulse)
WHRXY	Main group current position acquisition (Cartesian coordinate: mm, degree)
WHRXY2	Sub group current position acquisition (Cartesian coordinate: mm, degree)

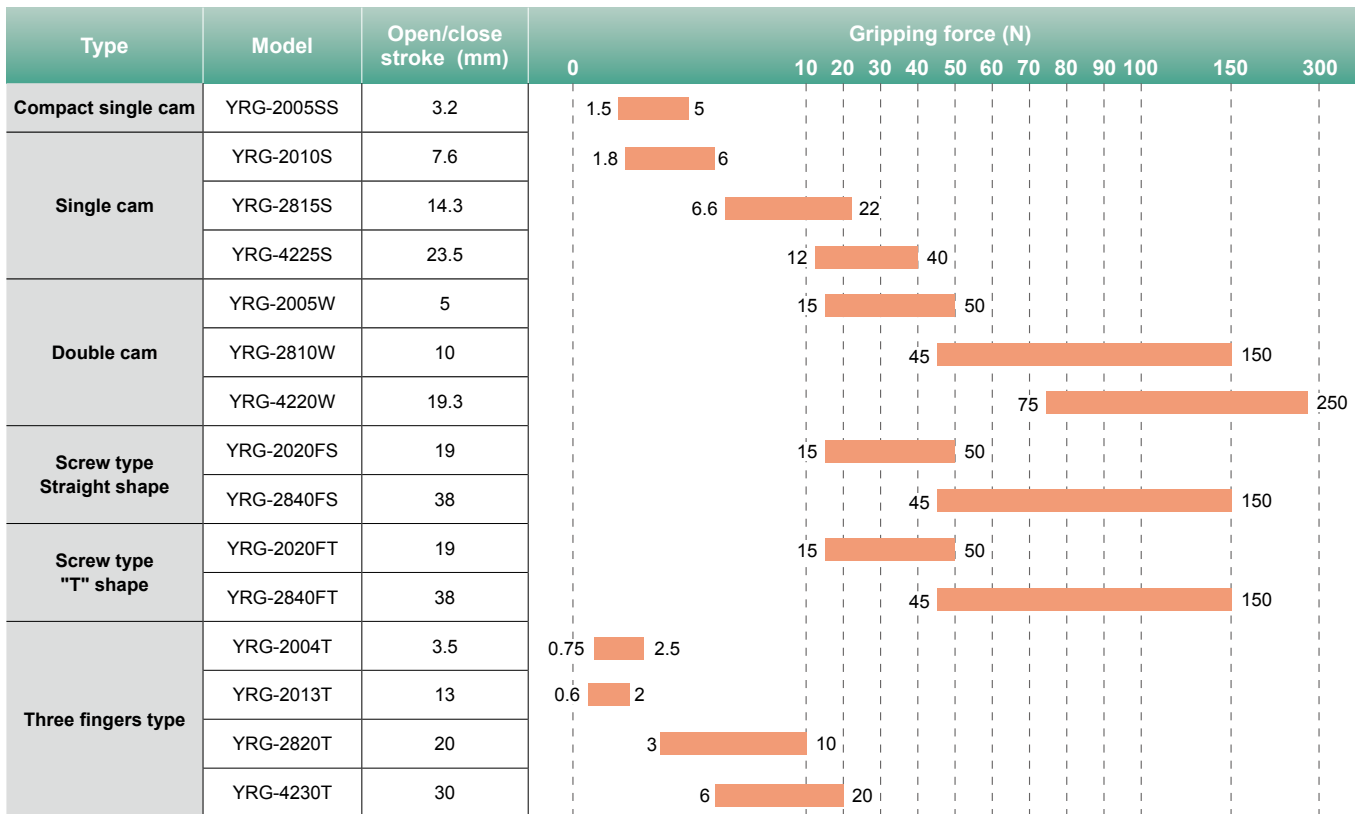
POINT 3

Combination with a vision system supports a wide variety of applications.

As the YRG series is combined with controller integrated robot vision "iVY System", the operations from the positioning using the camera to workpiece handling can be controlled in the batch mode using the RCX240/RCX340 controller. Sophisticated systems can be easily configured.

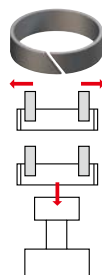
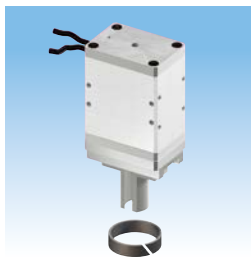


Gripping force comparison of electric gripper models



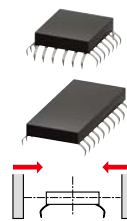
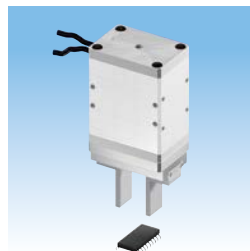
Application examples

Deformation prevention transfer of resin rings, etc.



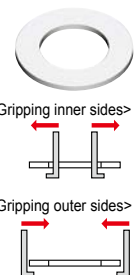
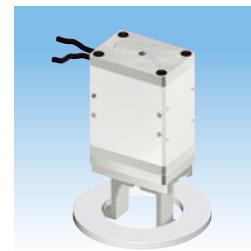
- Measuring function
 - Gripping force control
 - Speed control
 - Multi-point position control
- (Maintains workpiece shape.)
(Maintains workpiece shape and prevents scratches.)
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(Applicable to many part types of workpieces.)

Chip assembly transfer Deformation prevention and lead protrusion dimension check



- Measuring function
 - Gripping force control
 - Speed control
 - Multi-point position control
- (Checks lead protrusion dimensions.)
(Maintains workpiece shape and prevents scratches.)
(Maintains workpiece shape and prevents scratches.)
(Applicable to many part types of workpieces.)

Transfer and dimension check of flexible workpieces with different sizes



- Measuring function
 - Gripping force control
 - Speed control
 - Multi-point position control
 - Reduction of setup work
- (Checks lead protrusion dimensions.)
(Prevents workpiece deformation.)
(Prevents scratches.)
(Applicable to many part types of workpieces.)
(Improves productivity.)

Note. Air unit cannot control the gripping force and speed, causing workpiece to be scratched or tact time not to be shortened.